

ΕΛΛΗΝΙΚΗ ΔΗΜΟΚΡΑΤΙΑ  
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& ΜΗΧΑΝΙΚΩΝ ΥΠΟΛΟΓΙΣΤΩΝ

# Acceleration and Optimization for Real-Time Multimodal Processing on the Edge

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## Advisory Committee

**Konstantinos Siozios** - Associate Professor

**Nikolaos Konofaos** - Professor

## Defence Committee

**Nikolaos Asimopoulos** - Professor

**Nikolaos Ploskas** - Associate Professor

**Georgios Fragoulis** - Professor

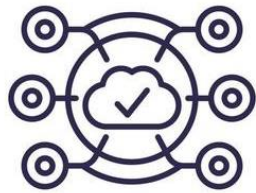
**Stergios Ganatsios** - Professor

# Overview



- Introduction
- Problem Definition
- Objectives and Contribution
- Methodology
- Results
- Discussion
- Conclusion





## Multimodal Edge Processing

Processing data closer to the source (the "edge") using multiple modalities for enhanced accuracy



## Advantages

Reduced latency

Improved privacy and security

Increased robustness and accuracy



## Challenges

Resource constraints

Dynamic real-world environments

Deployment and management

# Research Gaps and Challenges



- Edge devices have **constraints** in **processing power** and **memory**, compared to cloud servers.
  - Our solution: Propose **algorithms** and **techniques** specifically **designed for resource-constrained edge devices** and utilizing specialized **hardware accelerators**.
- Real-world conditions are constantly changing, making **single sensor data unreliable**.
  - Our solution: Employing sophisticated algorithms to effectively **combine data** from **multiple sensors** and provide a **comprehensive view of the environment**.
- Deployment and Management Complexity
  - Our solution: Develop a centralized management platform that can **seamlessly orchestrate** the **deployment, configuration**, and **monitoring of edge devices**.



# Thesis Objectives and Contributions



This thesis addresses the aforementioned challenges by proposing a new methodology that resulted in an **accelerated multimodal framework** tailored for **edge** computing.

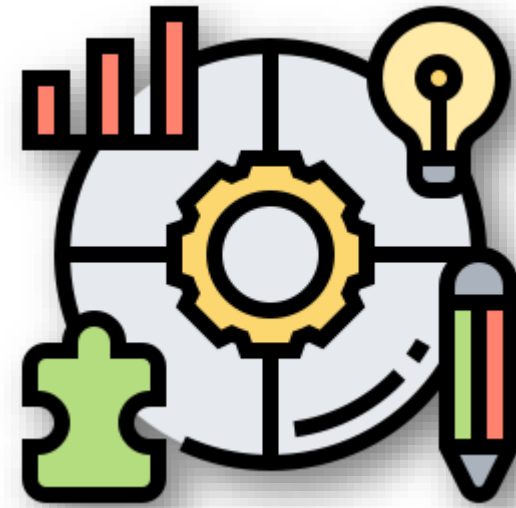
**Key objective:** Enable the processing of complex data directly at the source leveraging hardware accelerators and optimized AI models and evaluate in real-world applications:

1. Provide **accelerated** computational processing using **hardware designs** for color transformations, edge detection, noise reduction.
2. Introduce **multimodal DL approaches** with **data fusion, optimized for edge applications** for abnormal event detection, object detection, proximity assessment, facial identification.
3. Present an extensive **evaluation** on **real-world datasets** and **deployment scenarios** in **public transportation**.





# Methodology



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ACCELERATION AND OPTIMIZATION FOR REAL-TIME MULTIMODAL PROCESSING  
ON THE EDGE

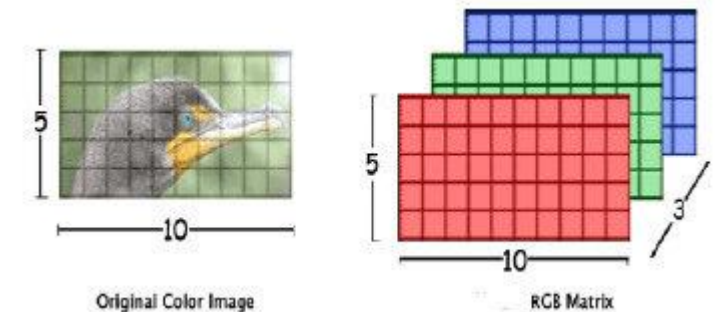
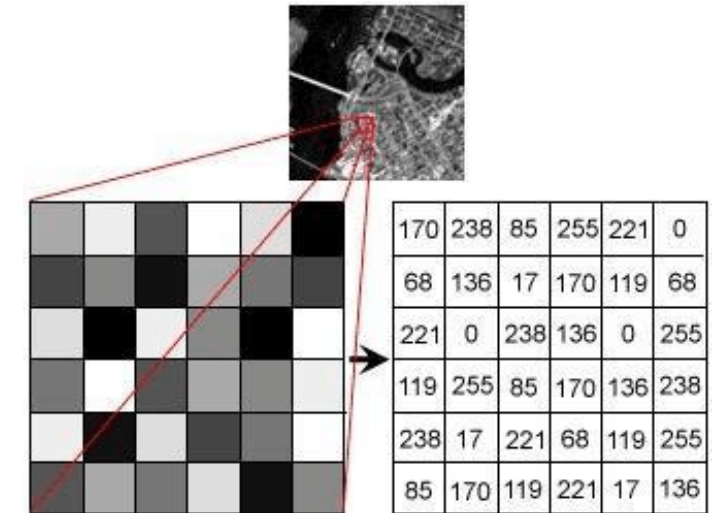
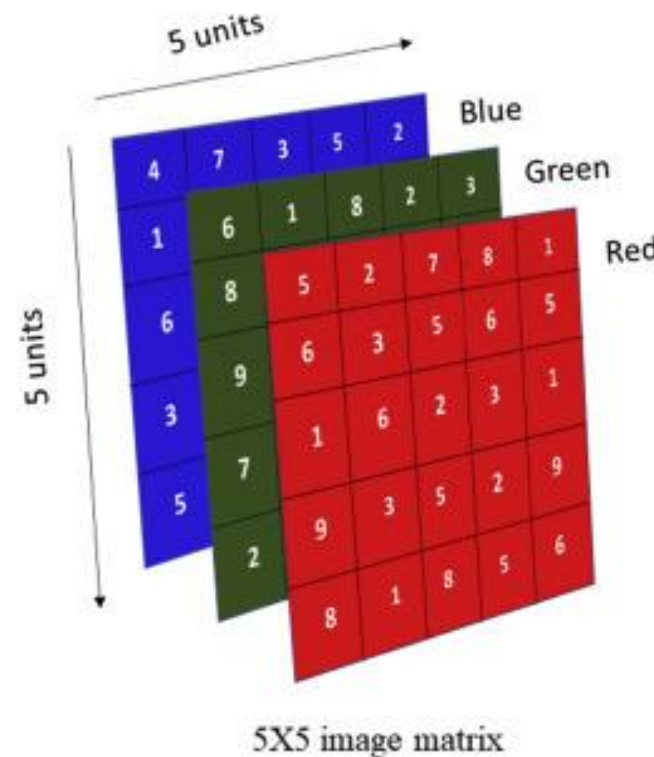


# Acceleration using CV Hardware Designs



## WHY?

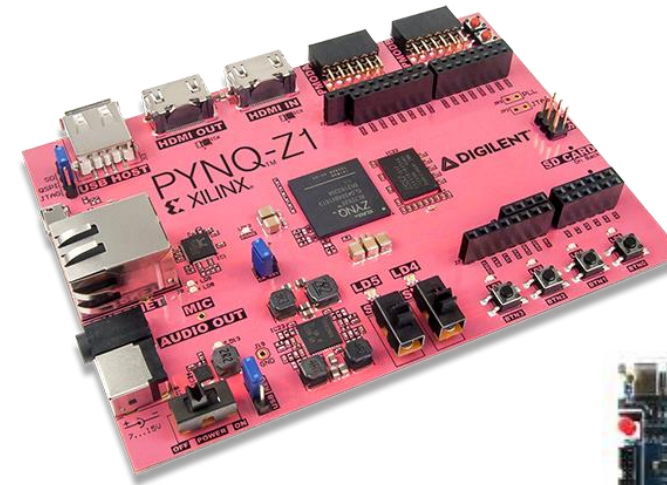
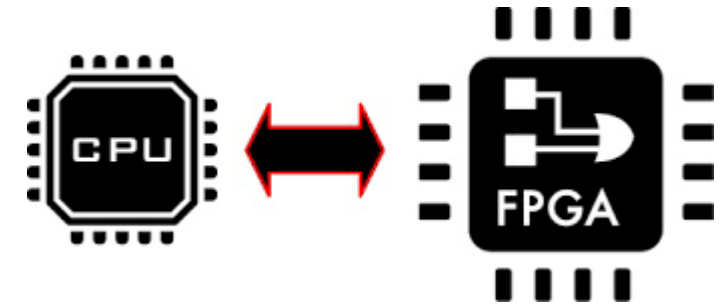
- Digital images are composed of **millions** of tiny dots called **pixels**, each representing a single color.
- Processing each pixel **individually** in a traditional, **sequential processor** is incredibly **time-consuming**, especially for high-resolution images.
- **Parallel processing** enables multiple processing units to work on different parts of the image **simultaneously**, dramatically **accelerating** the overall **processing speed**.



# Acceleration using CV Hardware Designs



- Leverage **hardware parallelism** to achieve substantial acceleration in image processing at the edge, bypassing the limitations of sequential processing in traditional **CPU-based** approaches.
- **Design hardware accelerators to offload common image transformations:**
  - Fast Color Conversion
  - Sobel Edge Detection
  - HLS-Based Edge Detection
  - Noise Reduction using Image Stacking





# Sobel Edge Detection

- Calculates the gradient of image intensity at each pixel, indicating the direction and magnitude of the steepest ascent.
- Involves convolving the image with two 3x3 kernels, one for horizontal edges and one for vertical edges.
- Implemented on Altera Cyclone IV EP4CE115 FPGA device.
  - A grayscale module converts color images to grayscale.
  - An edge detection module implements a Sobel Edge Detection algorithm for highlighting edges in grayscale images.
- Achieved 98ms with only 1W average power consumption on 640x480 images.

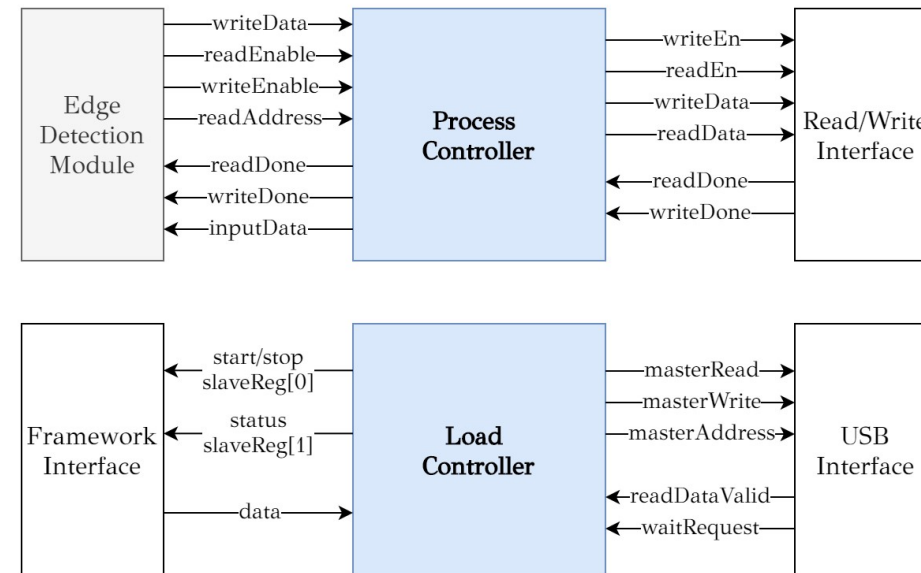


-1	0	+1
-2	0	+2
-1	0	+1

Gx

+1	+2	+1
0	0	0
-1	-2	-1

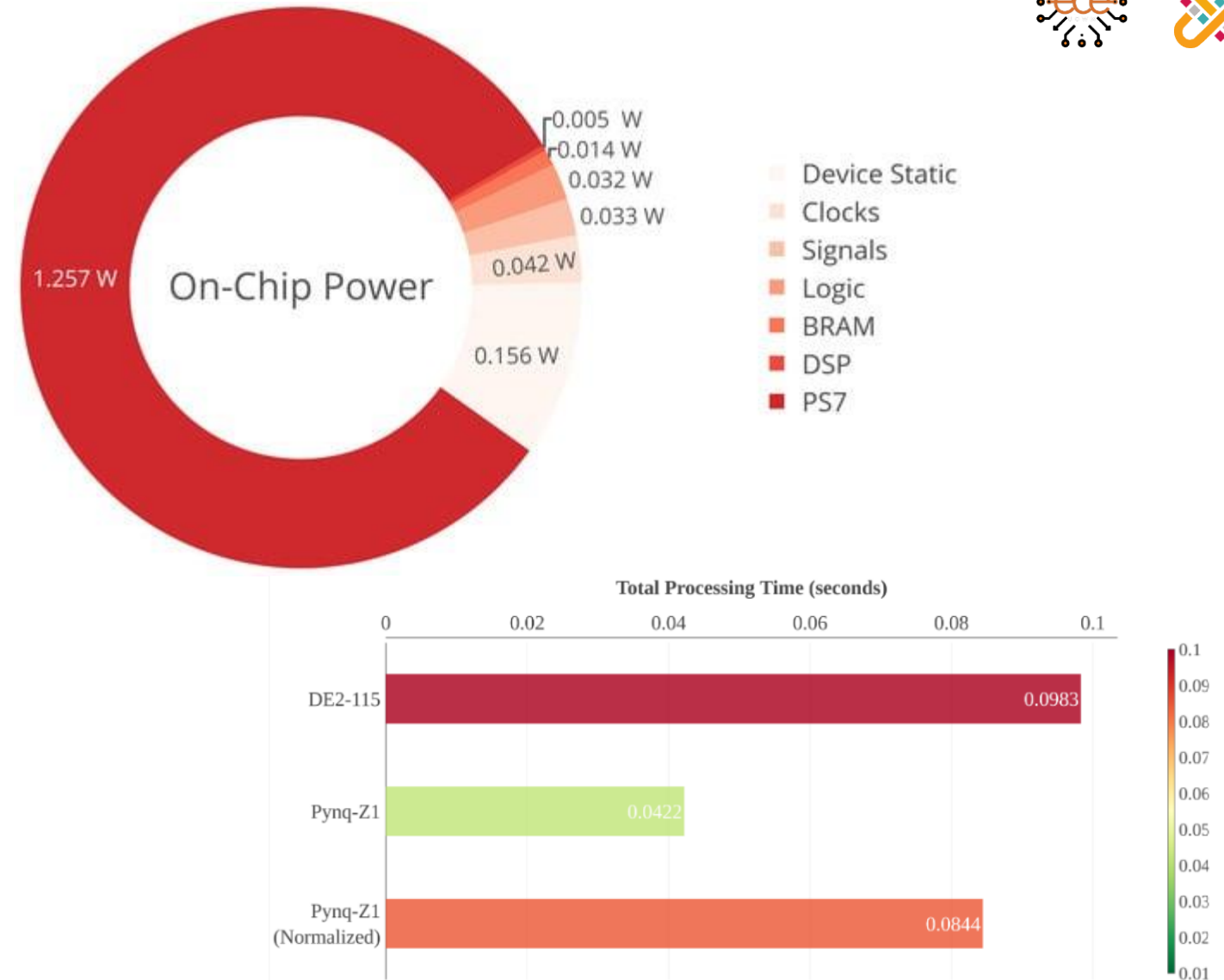
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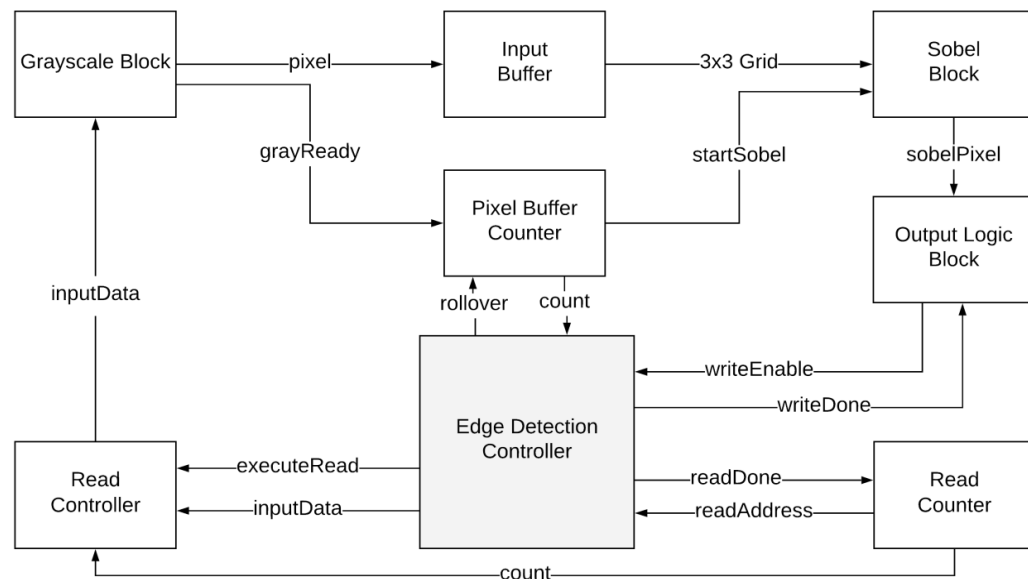
**D. Tsiktsiris**, D. Ziouzos, M. Dasygenis, "A Portable Image Processing Accelerator using FPGA", 2018 7th International Conference on Modern Circuits and Systems Technologies (MOCASST), IEEE, 2018.

# HLS Edge Detection

- Implementation with High Level Synthesis using Vivado HLS.
- Sobel Edge Detection on Xilinx PYNQ-Z1
  - Unified grayscale and edge detection modules into a single processing core
  - Int2RGB IP for enhanced image reconstruction performance
  - AXI and DMA engines for component communication and fast data transfer
- Achieved 42ms with 1,5W average power consumption on 640x480 images.
- Compared with bare metal VHDL design the implementation was slightly faster



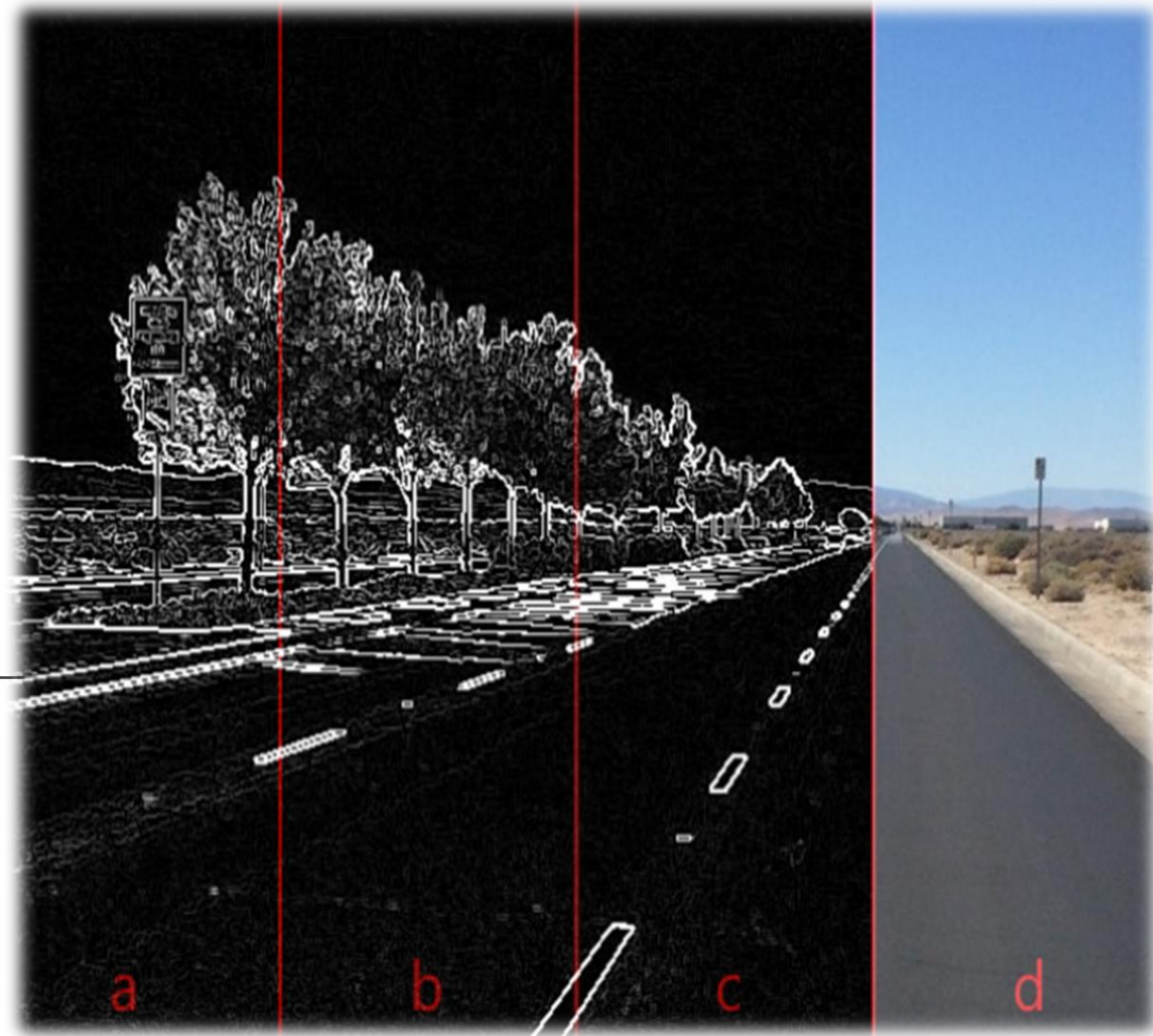
*D. Tsiktsiris, D. Ziouzos, M. Dasygenis. "A high-level synthesis implementation and evaluation of an image processing accelerator", Technologies 7.1 (2018): 4.*



## Architecture of the edge detection FPGA module

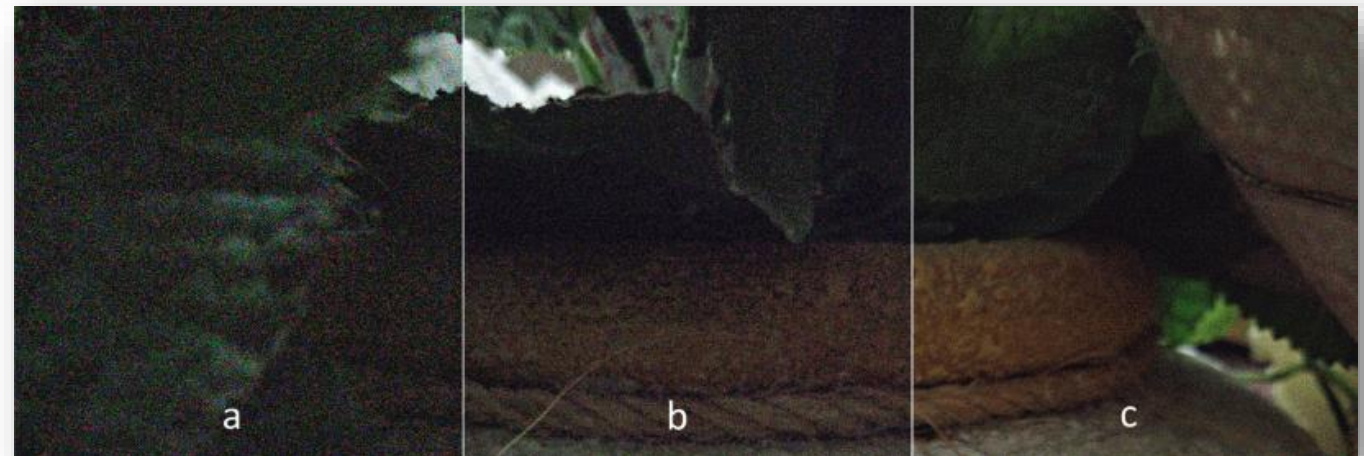
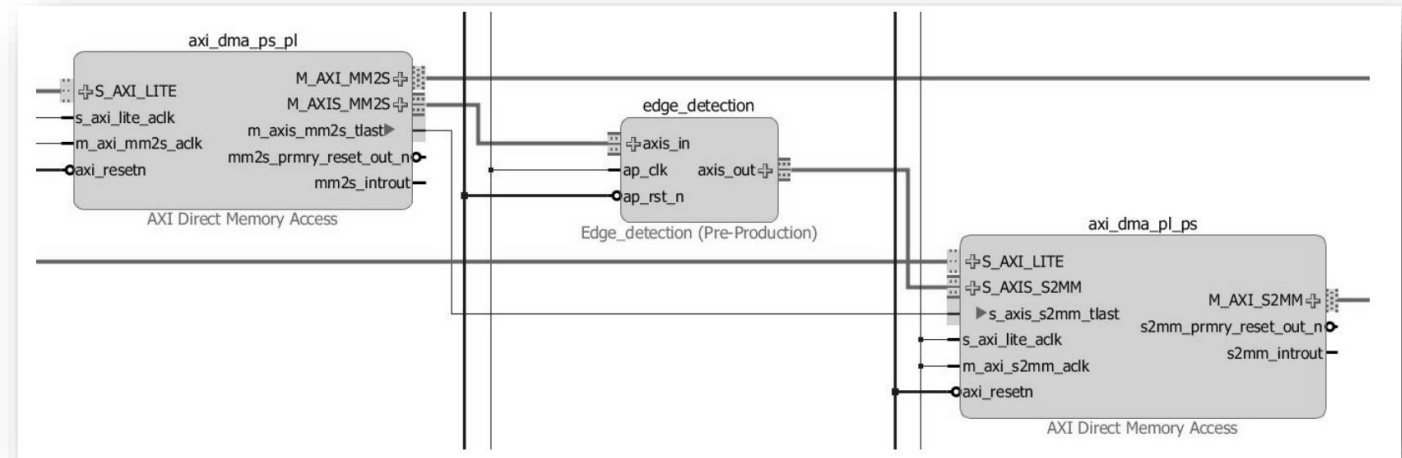
Functional diagram for the FPGA module

**D. Tsiktisiris**, D. Ziouzos, M. Dasygenis. "A high-level synthesis implementation and evaluation of an image processing accelerator", *Technologies 7.1* (2018): 4.



# Noise Reduction using Image Stacking

- Implemented on Xilinx Pynq-Z1 board using HLS
  - Buffer of multiple frames
  - Tile matching with pattern-based fuzzy heuristics
  - Tile merging across the buffer using color averaging to reduce noise and enhance dynamic range
- 200ms per 15 frames of 4000×3000 pixel resolution



**D. Tsiktsiris**, D. Ziouzos, M. Dasygenis. "HLS Accelerated Noise Reduction Approach Using Image Stacking on Xilinx PYNQ", 2019 8th International Conference on Modern Circuits and Systems Technologies (MOCAST), IEEE, 2019.



# Accelerated AI Approaches



*Part of this research was funded by H2020 AVENUE (Horizon H2020-ART-07-2017)*



## ACTION RECOGNITION

- Multimodal stream classification
- Pose classification
- Spatiotemporal autoencoder
- Hybrid LSTM classification
- Overhead abnormal event detection



## OBJECT DETECTION

- Overhead Fisheye Object Detection



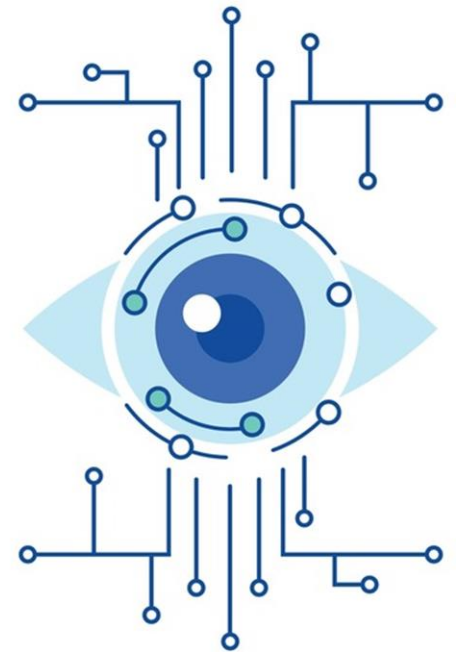
## AUDIO EVENT DETECTION

- Single Event Detection



## RE-IDENTIFICATION

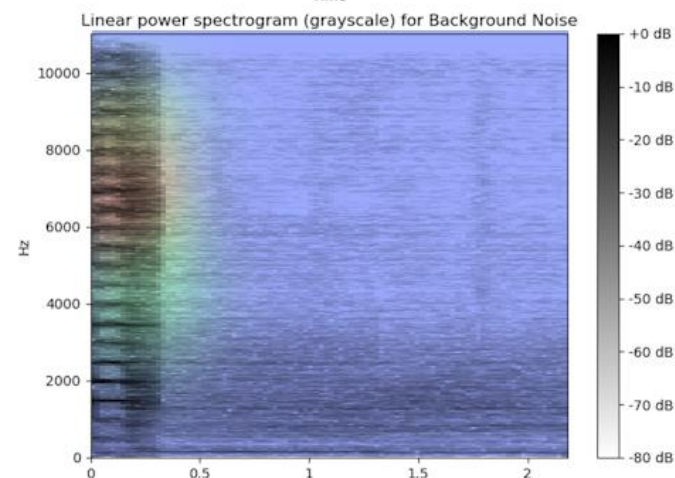
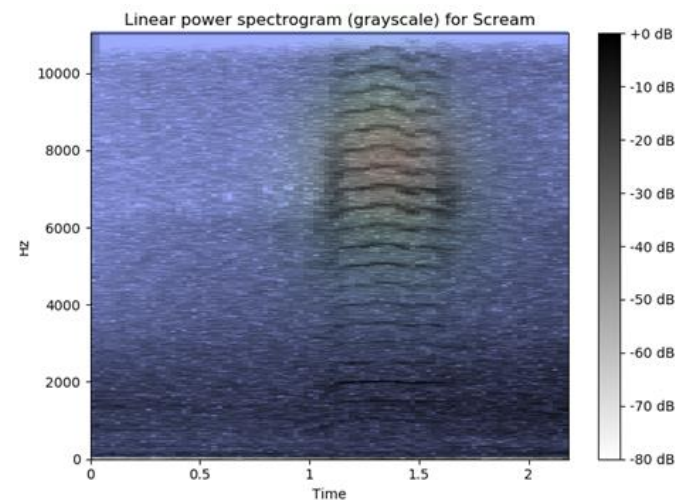
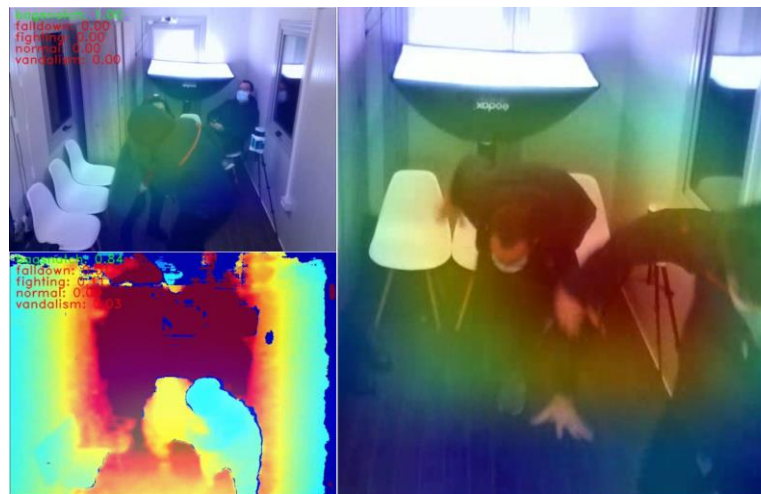
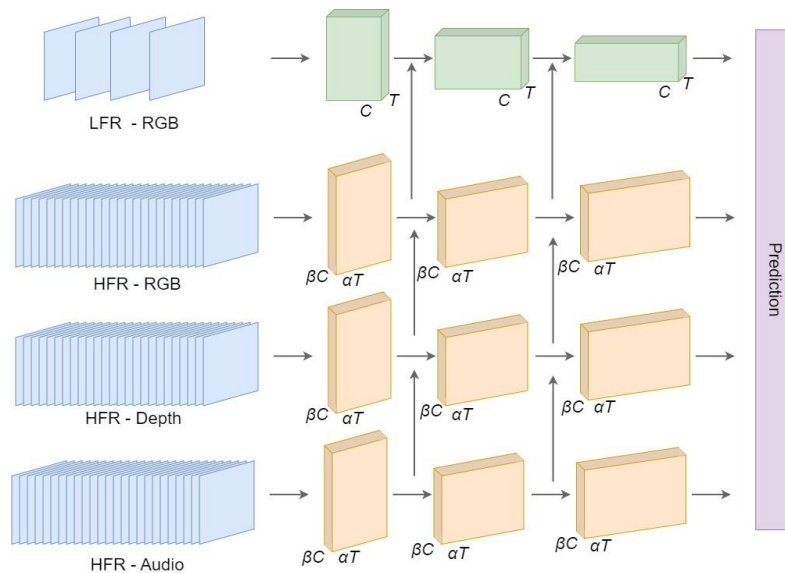
- Siamese facial verification



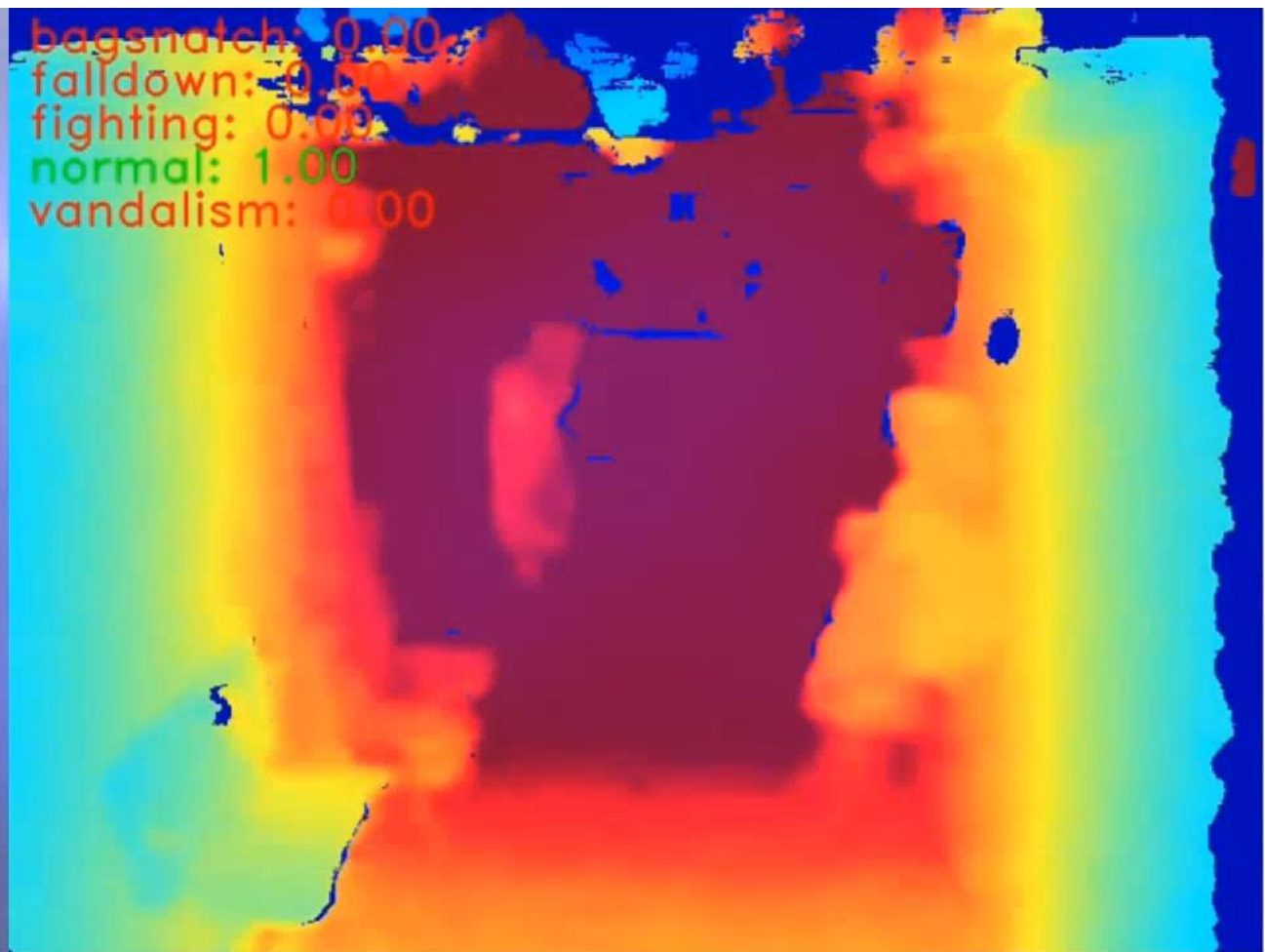


# Multimodal Stream Classification

- Abnormal Event Detection using RGB, Depth and Audio (Mel-Spectrograms)
- Employs four distinct pathways
  - Low-Frame Rate Path (LFR): Preserves spatial semantics from the RGB modality.
  - High-Frame Rate Paths (HFR): Focuses on temporal features from RGB, Depth and Audio modalities.
- Utilizes multi-level feature fusion using lateral connections
- Optimized for edge deployment through quantization, CUDA acceleration, layer fusion, and asynchronous data loading
- Achieves 85.1% Top-1 accuracy compared to 81.6% by MoviNet-A6 (RGB-Only)
- Drawbacks: Requires a complex training process, data alignment and synchronization

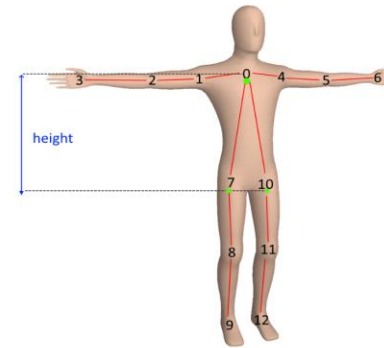


**D. Tsiktsiris**, A. Lalas, M. Dasygenis, K. Votis, "Multimodal Abnormal Event Detection in Public Transportation", IEEE Access, 2024.

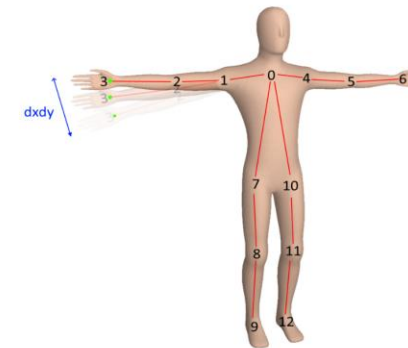


# Pose Classification

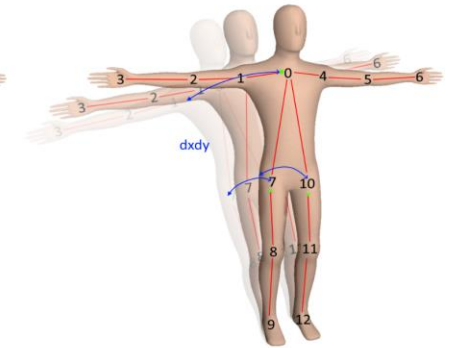
- Identifies abnormal behavior based on human pose trajectories
- Four-stage pipeline with pose estimation, tracking, feature extraction and classification.
- Utilizes LSTM network for classification based on extracted features from human poses
- Demonstrated 99.6% accuracy in classifying normal and abnormal behavior
- Drawbacks: Occlusion issues, Unbalanced datasets



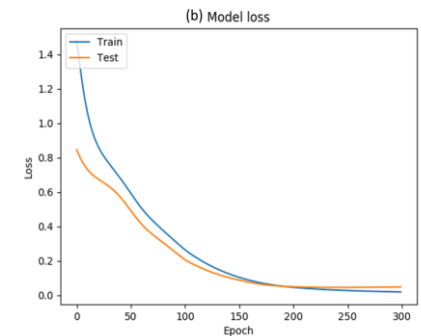
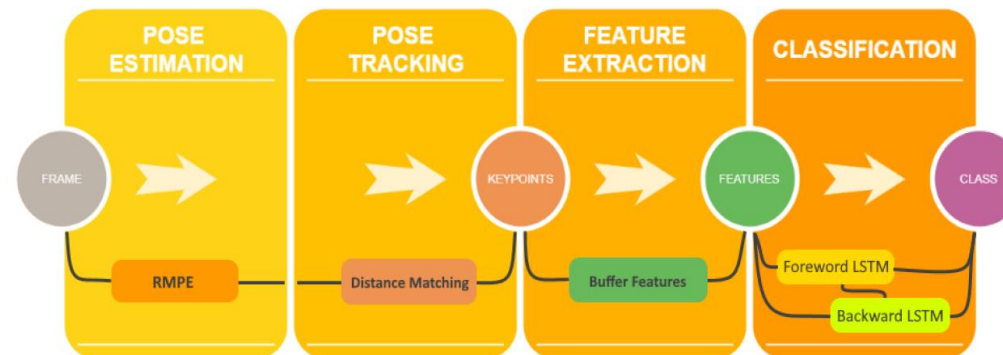
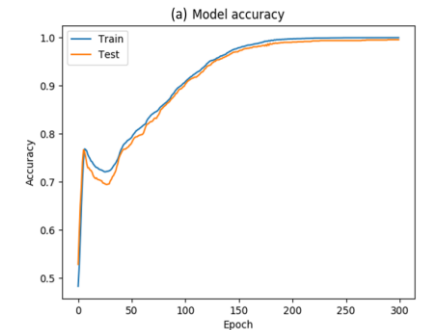
Normalized joint positions



Joint velocities



Center velocity



**D. Tsiktisiris**, N. Dimitriou, A. Lalas, M. Dasygenis, K. Votis, "Real-time abnormal event detection for enhanced security in autonomous shuttles mobility infrastructures", *Sensors* 20.17 (2020): 4943.







P1 normal

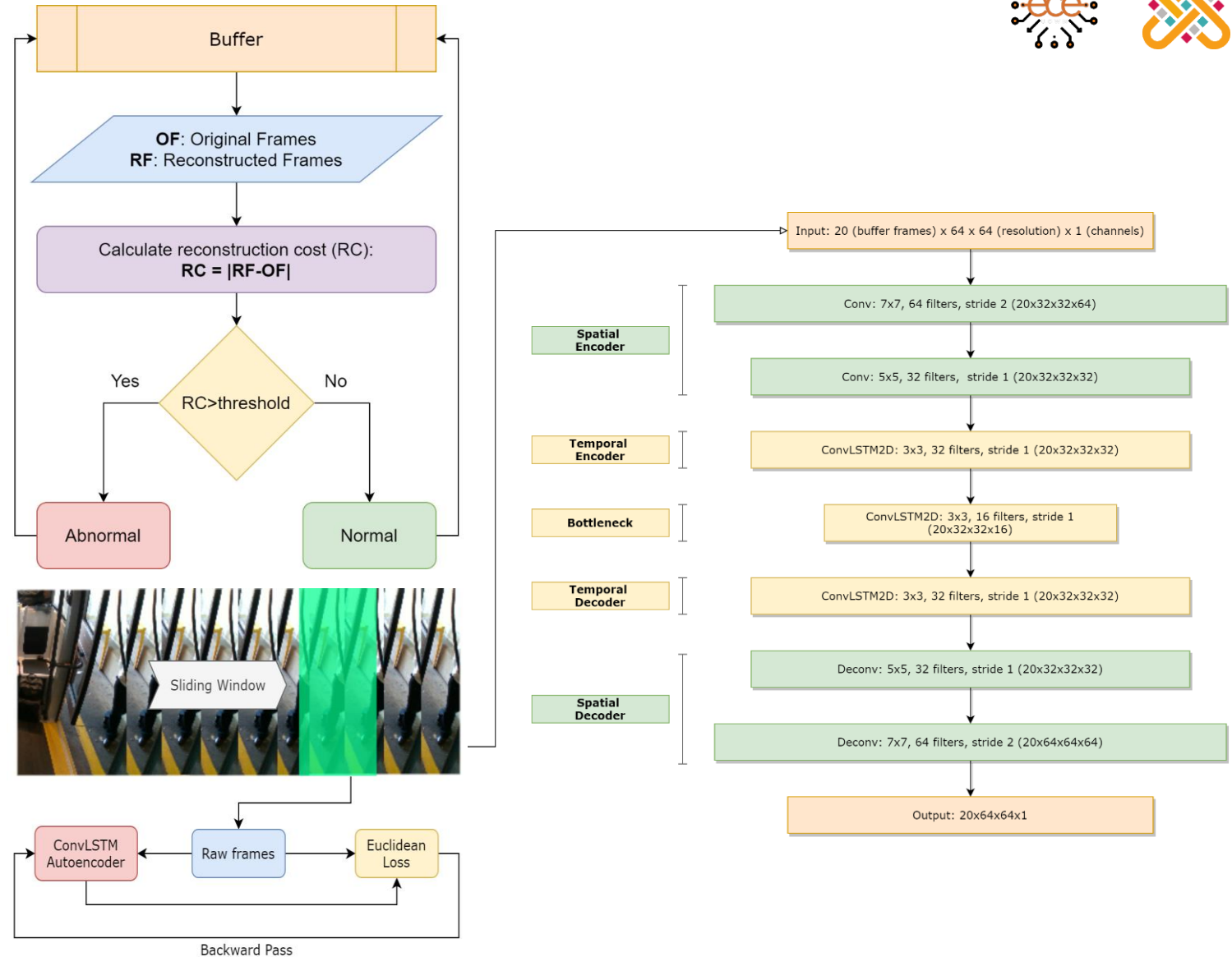
P2 normal

P: 2



# Spatiotemporal AutoEncoder

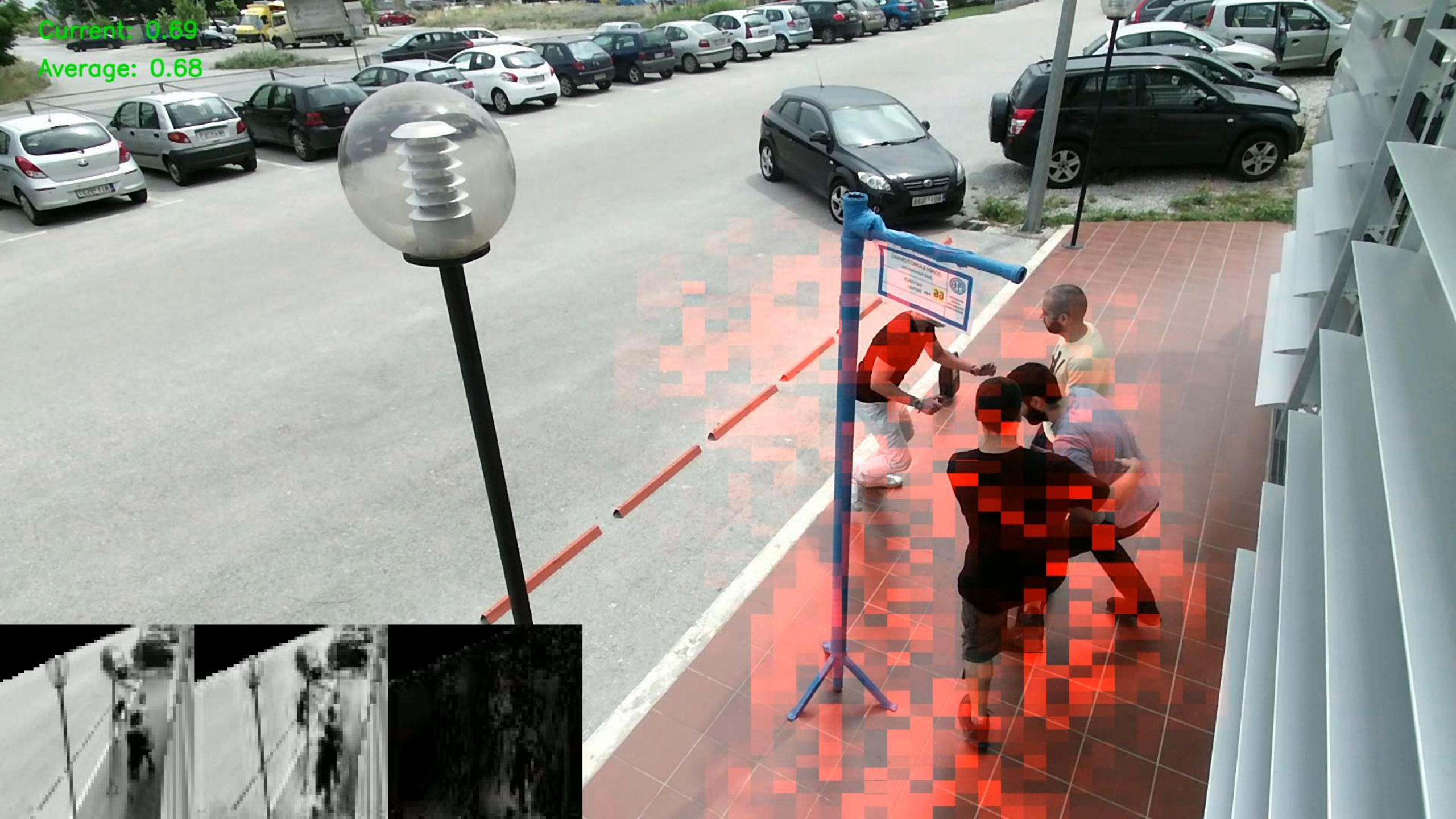
- Trained on normal video volumes to learn regular patterns and detect deviations
- Utilizes spatial convolution and a temporal encoder-decoder (LSTM)
- Bottleneck compression forces the network to learn a more compact and efficient representation of the temporal information.
- The difference between the reconstructed and original frames (reconstruction cost, RC) exceeds a threshold, the video buffer is classified as abnormal.
- Drawbacks: Binary only classification using thresholds in regularity score



**D. Tsiktsiris, N. Dimitriou, A. Lalas, M. Dasygenis, K. Votis, "Real-time abnormal event detection for enhanced security in autonomous shuttles mobility infrastructures", Sensors 20.17 (2020): 4943.**

Current: 0.69

Average: 0.68

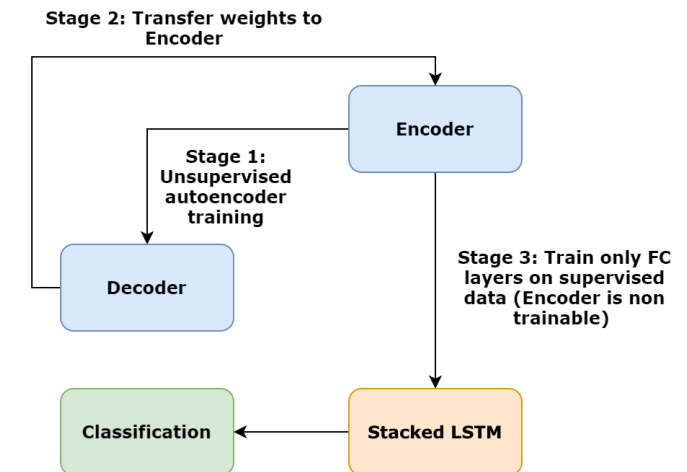
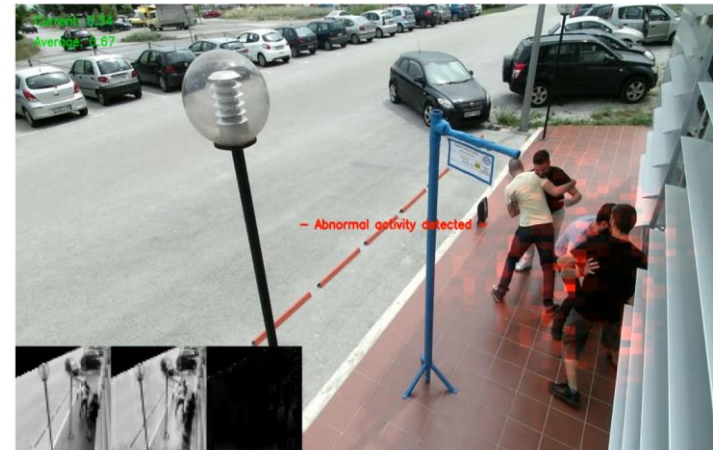
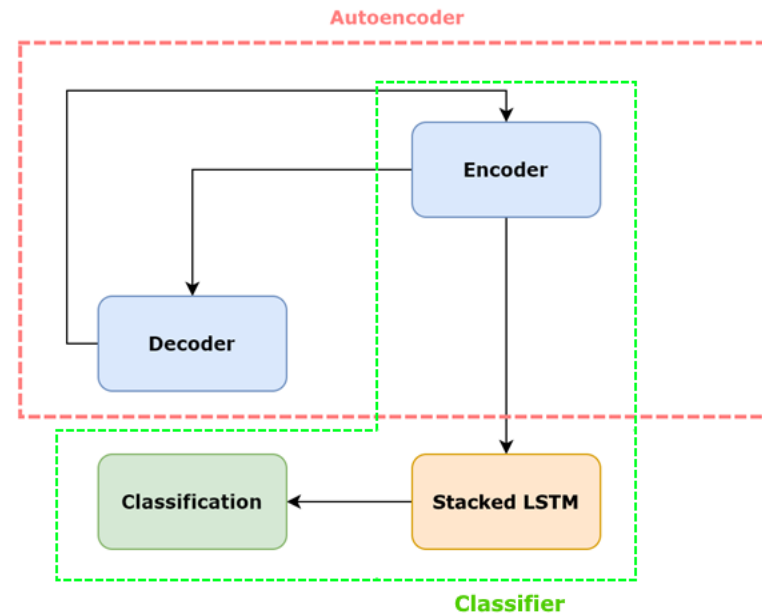






# Hybrid LSTM Classification

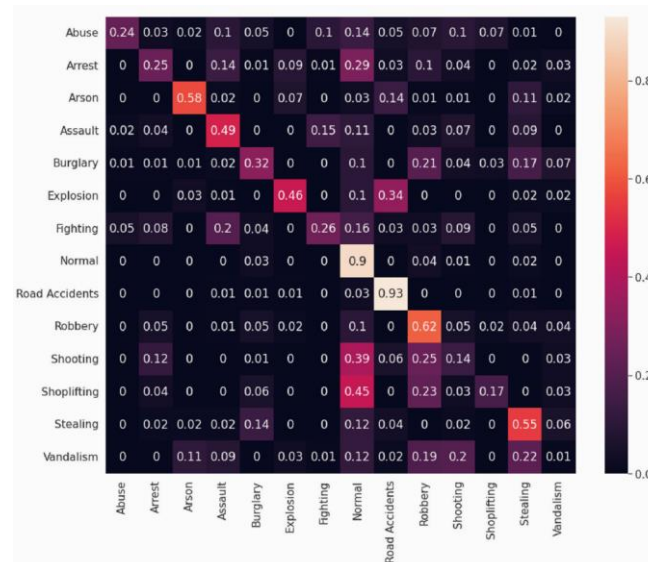
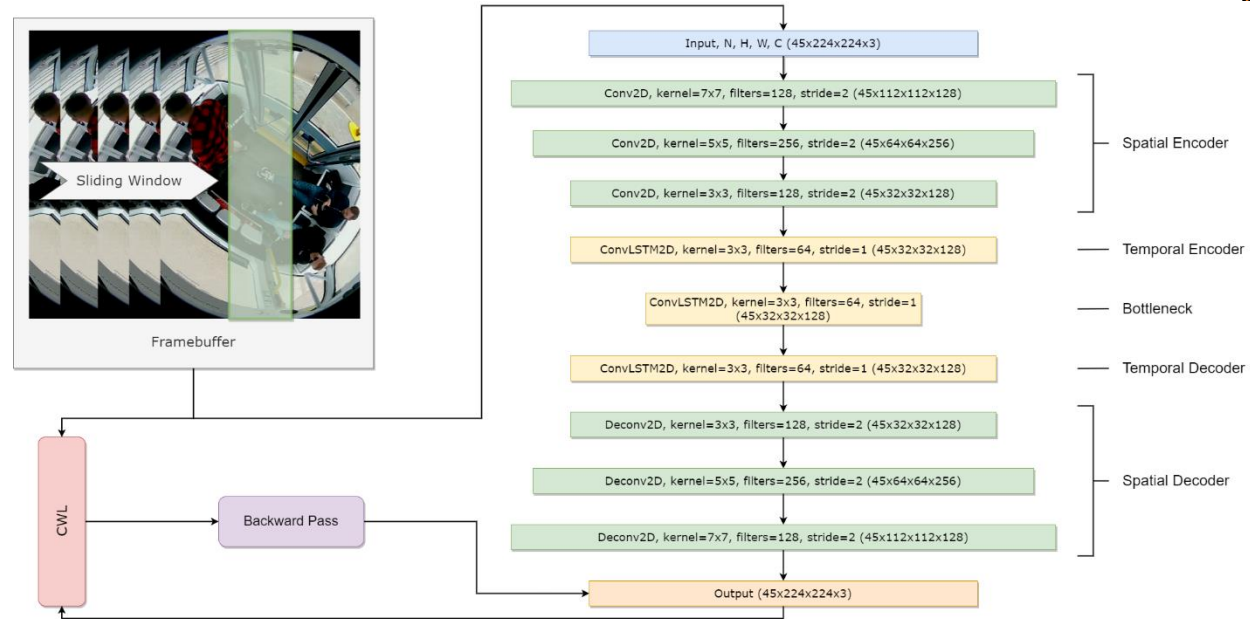
- Extends the previous method by incorporating a semi-supervised approach.
- Utilizes the encoder from the spatiotemporal autoencoder as a high recaller for anomalies
- Combines the encoder with an LSTM classifier for false positive reduction
- Achieves high recall and precision in anomaly detection
- Drawbacks: Complex two-stage training



**D. Tsiktisiris**, N. Dimitriou, A. Lalas, M. Dasygenis, K. Votis, "Real-time abnormal event detection for enhanced security in autonomous shuttles mobility infrastructures", *Sensors* 20.17 (2020): 4943.

# Overhead Abnormal Event Detection

- Utilizes CAE with fisheye overhead perspective for occlusion free anomaly detection
- Designed to capture important features while removing noise and redundancy
- Employs a Center Weighted and Scale Invariant Loss function for accurate reconstruction of the central image area
- Trained in two phases:
  - Unsupervised learning for capturing regular patterns
  - Supervised learning for anomaly classification
- Achieved 88% Top-1 accuracy vs 86% Chen et al. [18]

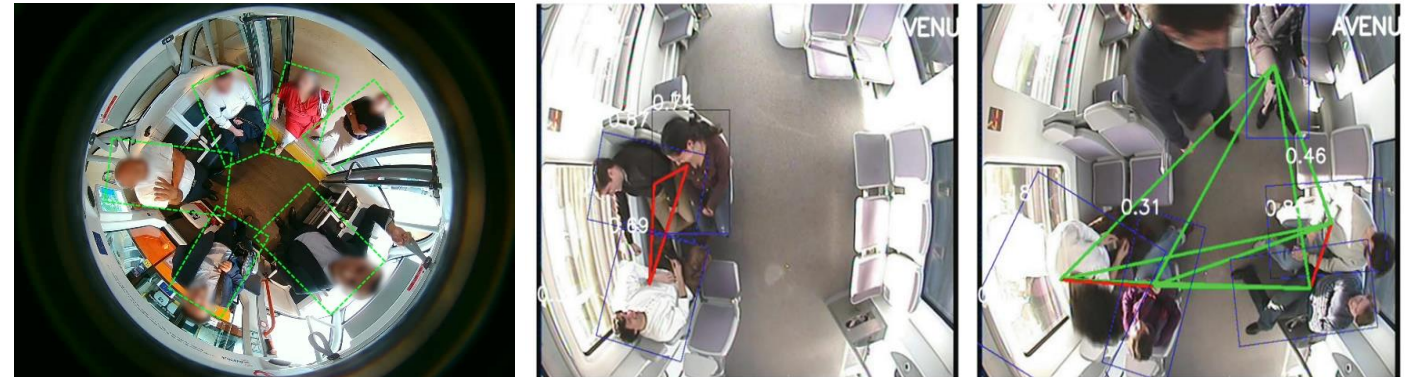
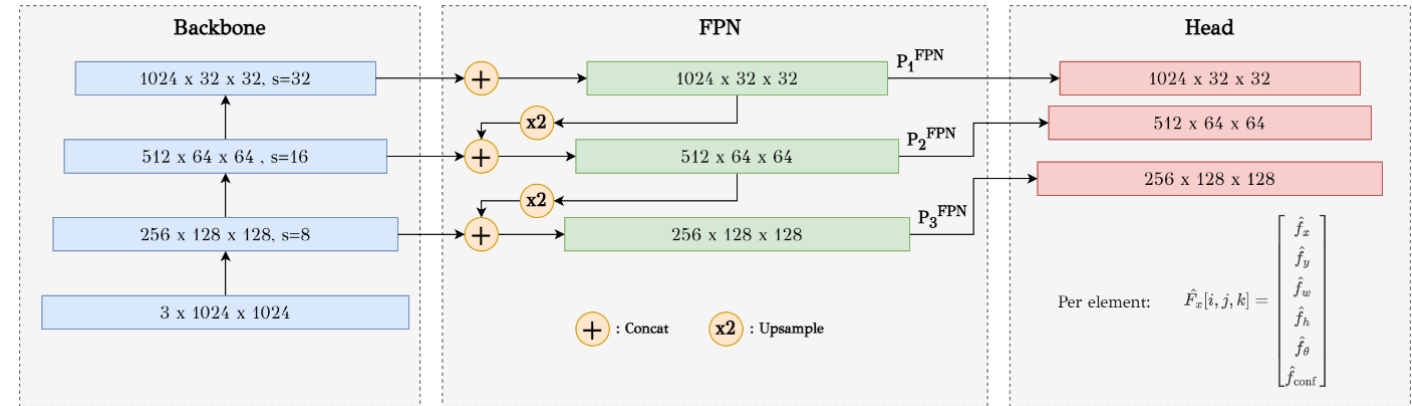


**D. Tsiktisiris, A. Lalas, M. Dasygenis, K. Votis, "Enhancing the Safety of Autonomous Vehicles: Semi-Supervised Anomaly Detection With Overhead Fisheye Perspective", IEEE Access, 2024.**



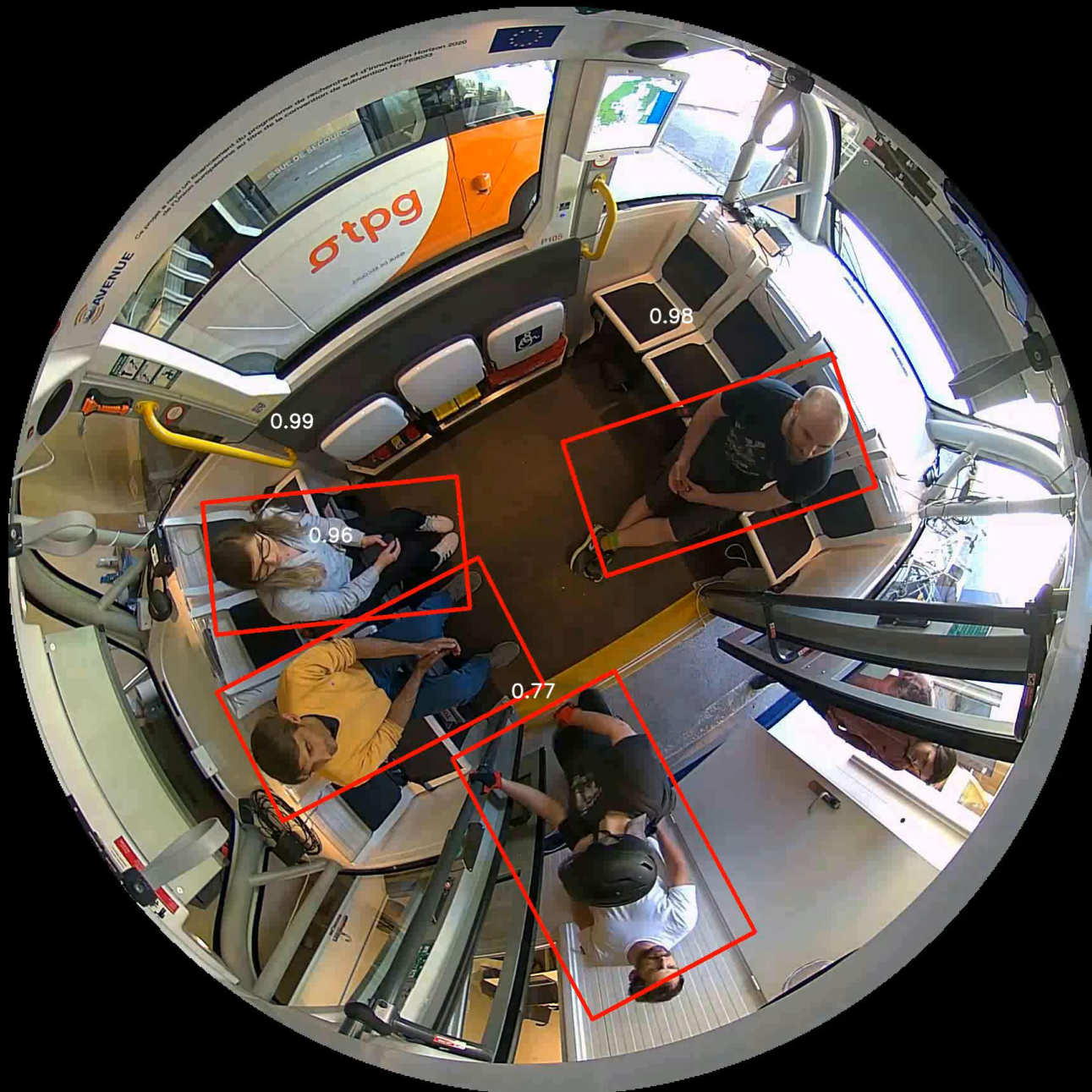
# Overhead Object Detection

- Object detection in overhead fisheye images
- Employs a three-stage architecture:
  - Backbone network (feature extractor)
  - Feature pyramid network (FPN)
  - Bounding box regression network
- Utilizes rotation-aware bounding box regression for accurate object localization and orientation in fisheye images
- Achieves 92.3% accuracy in overhead passenger detection vs 87% by [32]



**D. Tsiktisiris**, A. Lalas, M. Dasygenis, K. Votis, "Improving Passenger Detection With Overhead Fisheye Imaging", *IEEE Access*, 2024.

**D. Tsiktisiris**, A. Lalas, M. Dasygenis, K. Votis, D. Tzovaras, "An efficient method for addressing covid-19 proximity related issues in autonomous shuttles public transportation". Cham: Springer International Publishing, 2022.





# In-vehicle security

Enhance the sense of security and trust



Video Modality Status

No abnormal events are detected

Event History

- Found Christian Zinckernagel in this vehicle!
- Found Sophie Green in this vehicle!
- Found Sophie Green in this vehicle!
- Found Sophie Green in this vehicle!
- Found Sophie Green in this vehicle!

2.52



Smart Feedback



Temperature	26.16°C	Smoking	No
CO2	679 ppm		
PM25	7 ppm		

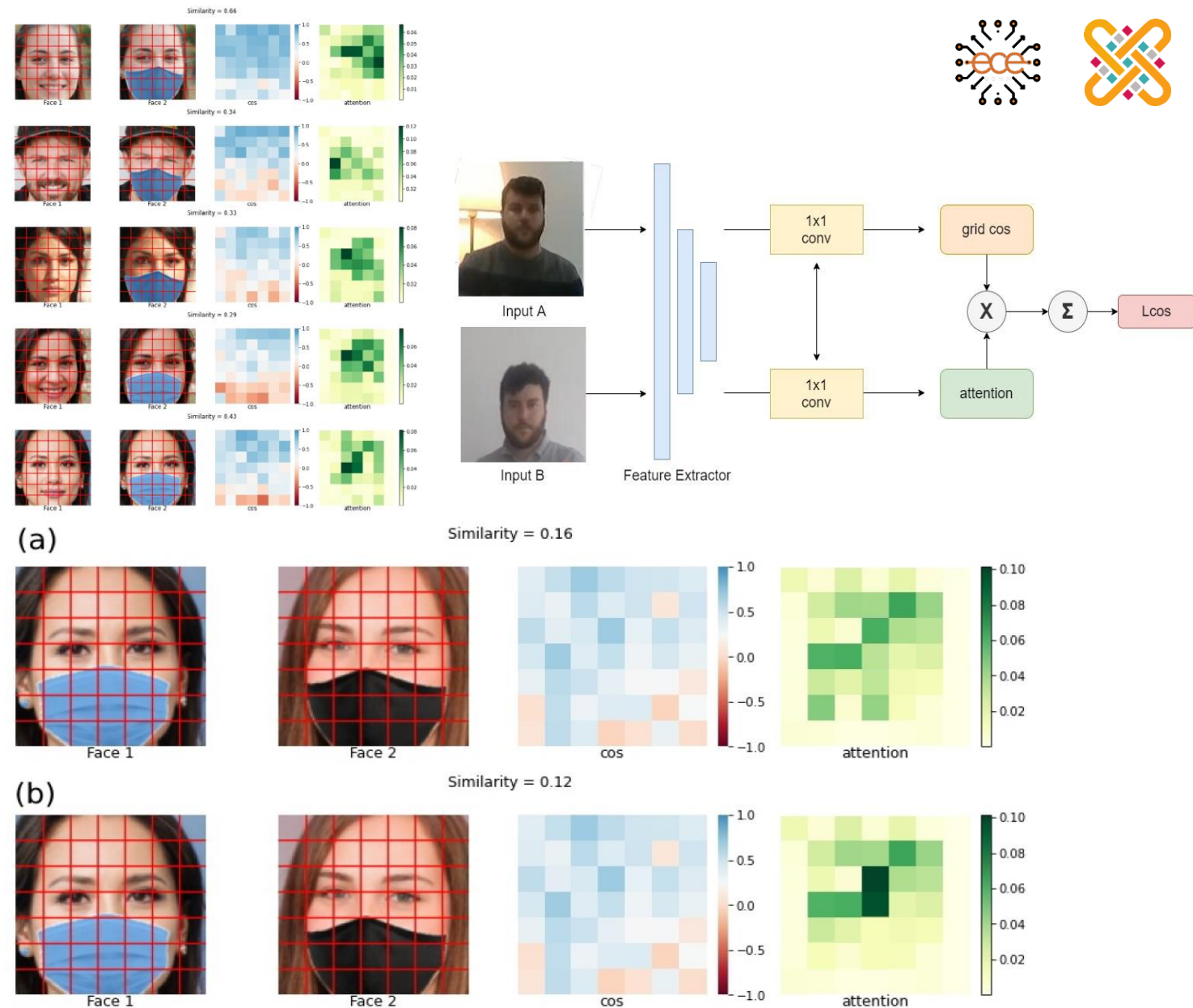


holo-vehicle-1, Slagelse, Denmark



# Facial Identification

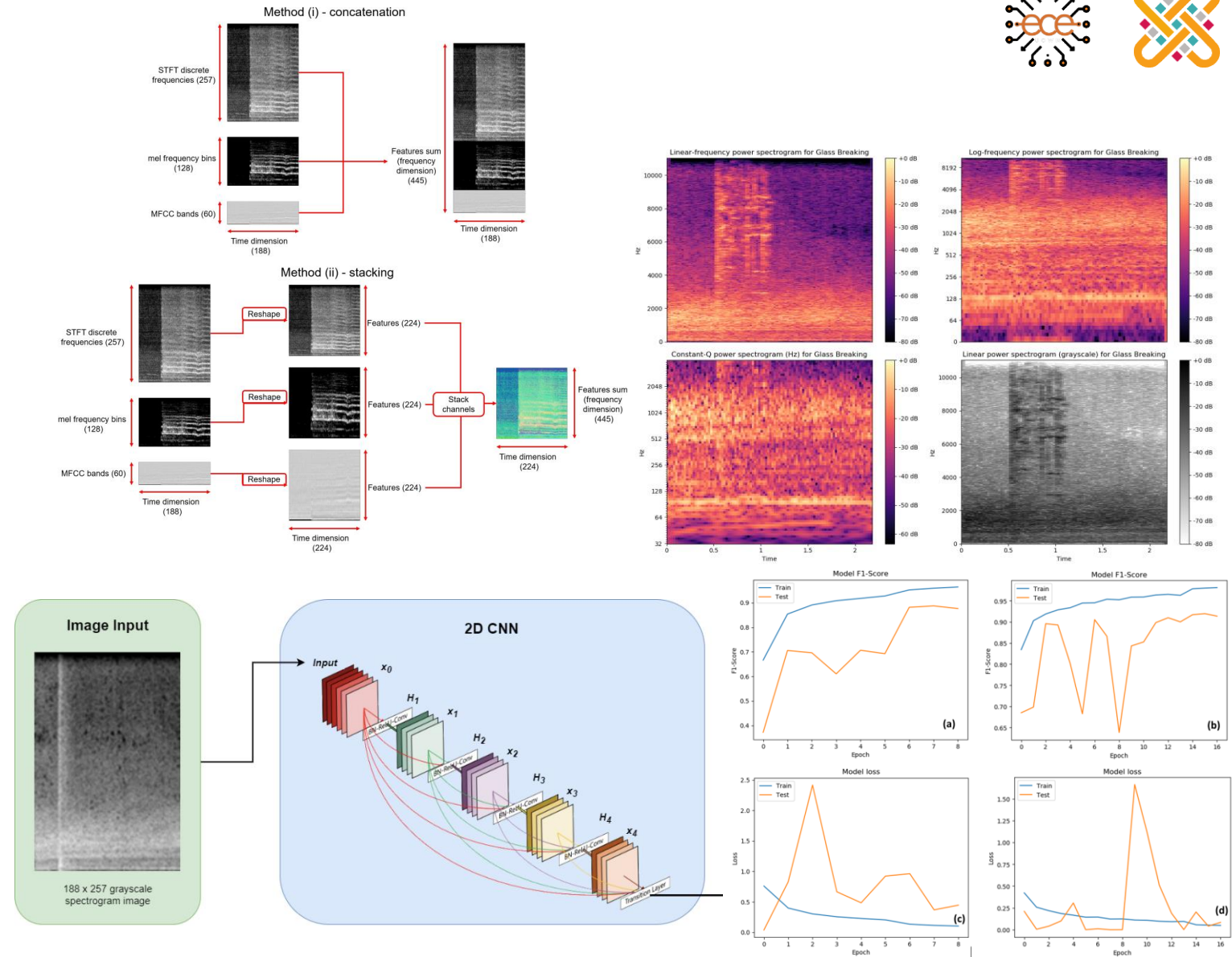
- Employs one-shot learning using a Siamese neural network for face verification.
  - Network learn to minimize distance for positive pairs and maximize distance for negative pairs.
  - Given two new face images, compute their embeddings (representations) in the learned space.
- Augmented existing datasets to include face masks for improved performance in real-world scenarios
- Achieved high accuracy of 99.35% in identifying individuals and 74.52% accuracy on datasets with face masks



**D. Tsiktsiris**, A. Lalas, M. Dasygenis, K. Votis, D. Tzovaras, "Enhanced Security Framework for Enabling Facial Recognition in Autonomous Shuttles Public Transportation During COVID-19". Cham: Springer International Publishing, 2021.

# Audio Classification

- Utilizes a DenseNet-121 CNN
- Investigated performance under various SNR settings
- Demonstrated high accuracy in classifying different audio events (gunshot, glass breaking, scream)
- Explored the generalizability of the network across different SNR environments



**D. Tsiktisiris**, Vafeiadis, A., Lalas, A., Dasygenis, M., Votis, K., & Tzovaras, D. (2022). A novel image and audio-based artificial intelligence service for security applications in autonomous vehicles. *Transportation Research Procedia*, 62, 294-301.



# Enhancing Safety in Public Transportation



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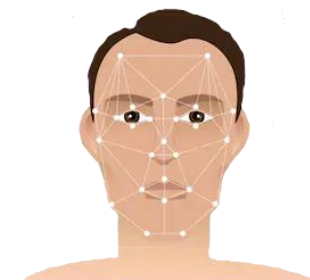
IN-CABIN MONITORING SERVICES FOR AUTONOMOUS VEHICLES AND  
INFRASTRUCTURE



# Problem Definition

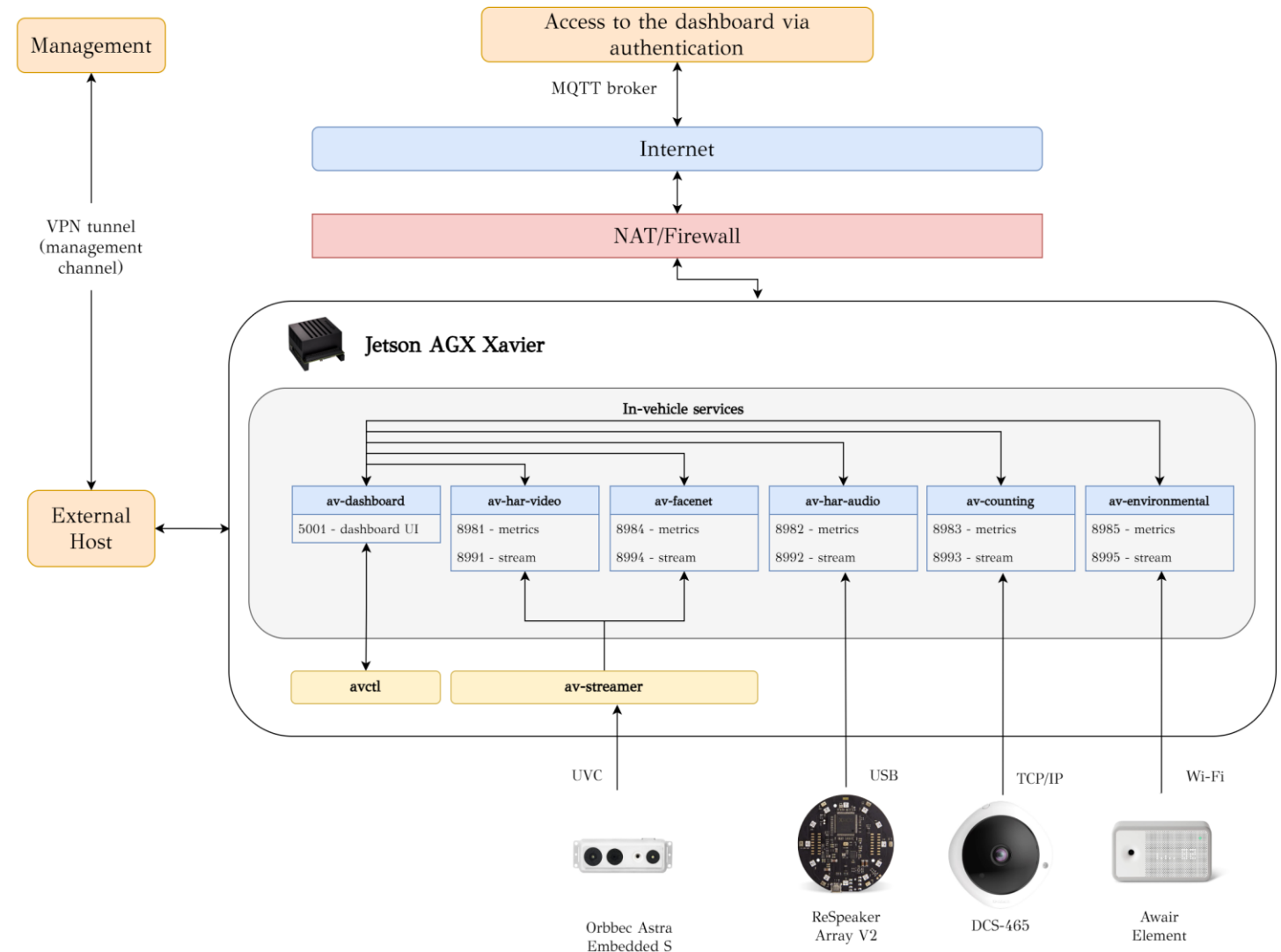


- Autonomous vehicles offer convenience but raise concerns about **passenger safety and security in the absence of a human driver**:
  - Passenger are concerned about their **safety** inside the vehicle in response to internal threats or emergencies
- **Objective:** Boost passenger confidence, enabling independent use of public transportation
  - Detect and notify about **abnormal events** (aggression, abnormal incidents, vandalism, petty crimes)
  - Provide accurate **passenger counting** for resource optimization and safety
  - Implement **facial recognition** for personalized monitoring and security

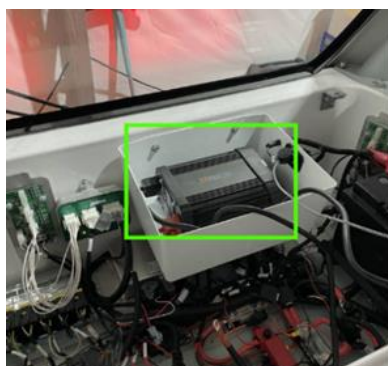


# In-Cabin Monitoring System

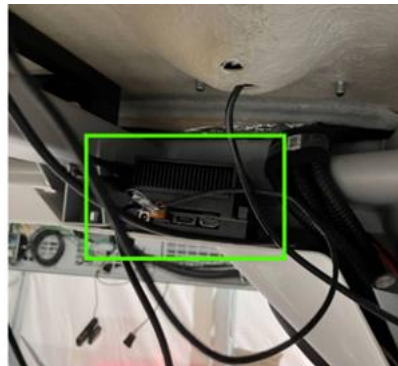
- Modular design with specialized sub-modules for real-time:
  - Audio and video data processing
  - Passenger counting, proximity assessment and facial recognition
  - Behavior analysis
- Utilizes a common foundation of hardware and sensors
- Efficient operation under 20 Watts in total using the Jetson AGX Xavier
- 5G connectivity for metadata transmission and management through VPN



# Real-world Installation



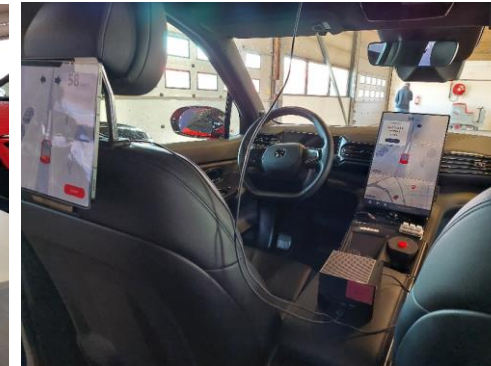
(a)



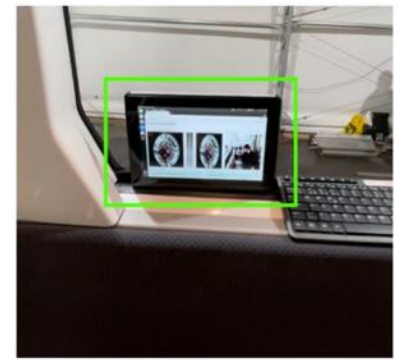
(b)



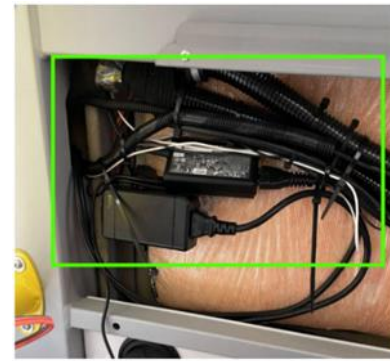
(c)



(d)



(e)



(f)



Real-world installation on NAVYA and Ruter autonomous minibuses in the context of the European H2020 projects AVENUE, SHOW, ULTIMO, AUTOTRUST

(a) Inverter

(b) Installation area – panel

(c) Overhead fisheye camera (D-Link DCS 4625)

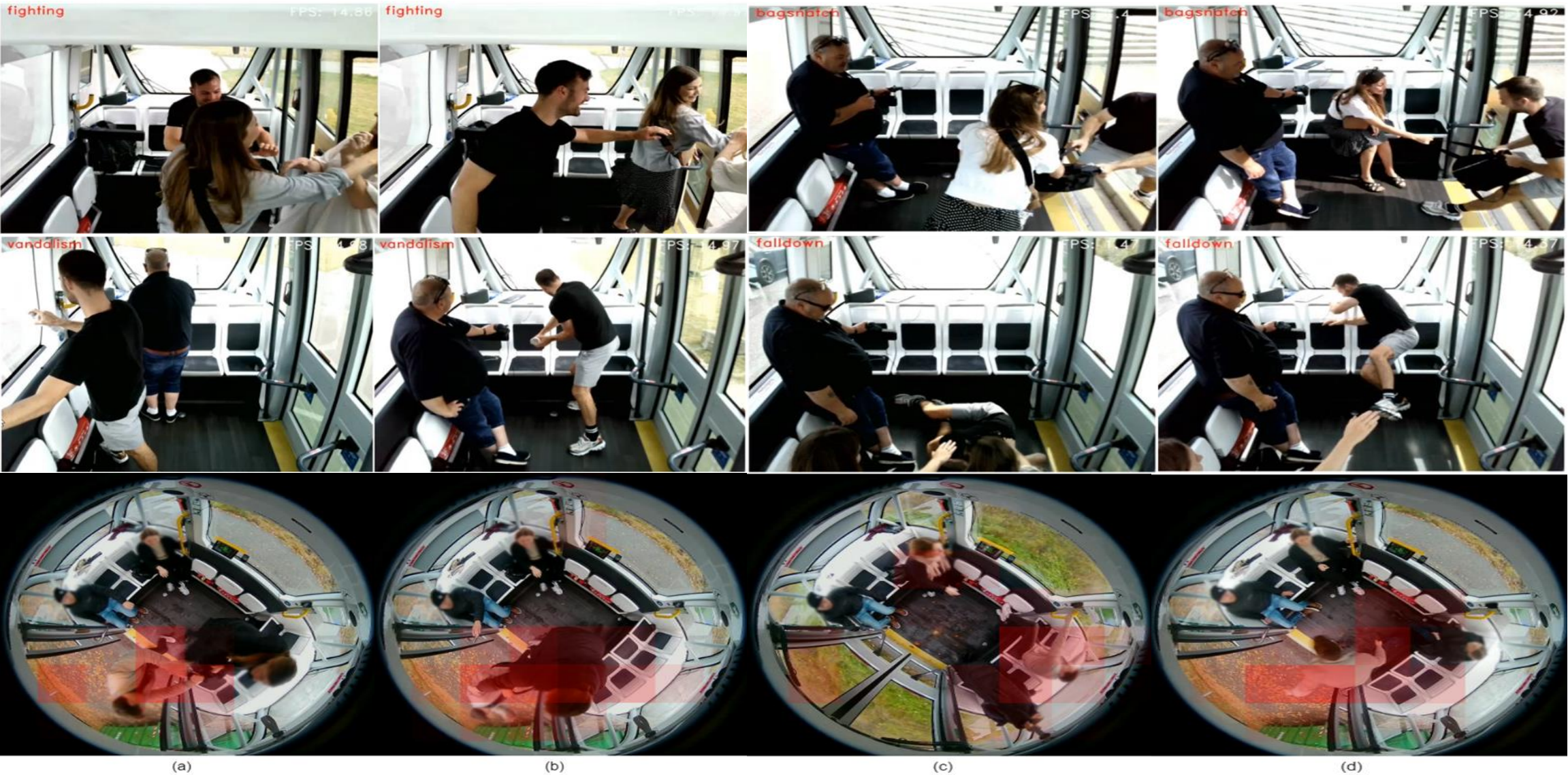
(d) Location of the NVIDIA Jetson AGX Xavier embedded system

(e) Monitoring screen for passengers

(f) Power-supply cables hidden behind the vehicle's panel



# Real-world Evaluation of Abnormal Events Detection





# Dashboard



## OBU Maintenance Dashboard

Augmented Security & Trust



Passenger Counting



Video

☐ Detected fighting (54%)

bagsnatch	14.80
fighting	54.17
normal	15.49
falldown	3.44
vandalism	12.09

Audio

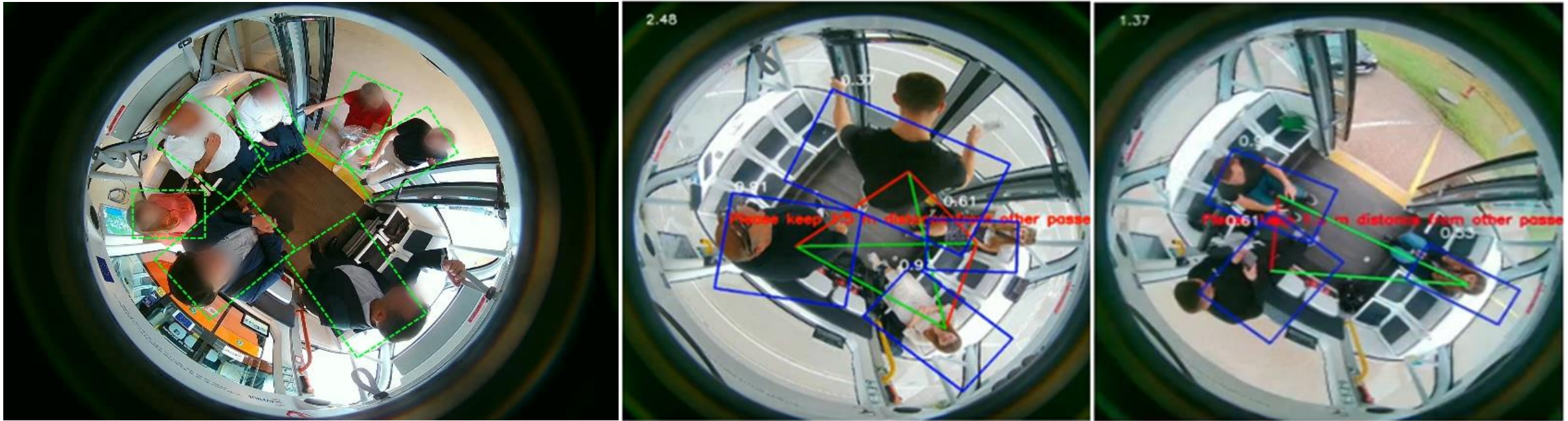
☐ No abnormal events

gunshot	15.05
screaming	15.05
speech	39.81
noise	15.05
glassbreaking	15.05

Detected Passengers: 0

n_pax	0
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# Real-time Passenger Proximity Detection



All passengers are correctly detected, even the two ones that are partially occluded

Green lines represent a safe distance, while red lines an unsafe one



# Real-World Face Identification Evaluation



Identification of the passengers inside the AV

- This dissertation has successfully demonstrated the potential of accelerated multimodal AI frameworks for **enhancing edge computing capabilities across various sectors**.
- The integration of multiple data modalities, hardware acceleration techniques, and software optimization strategies has enabled the development of **efficient systems** for **real-time applications**.
- The framework's practical value has been showcased through its successful implementation and **evaluation in real-world use cases** in public transportation.



# Future Work



- Explore advanced **privacy-preserving** techniques to address data privacy and security concerns
- Develop more **robust and adaptable** AI models capable of handling greater data diversity and complexity
- Implement **distributed training and inference** mechanisms for enhanced scalability in distributed edge computing environments
- Integrate the framework with emerging technologies, such as **AR/VR**, for novel applications in various domains





# Conclusion



- This dissertation has made a substantial contribution to the field of AI and edge computing by presenting an **accelerated multimodal framework** that effectively addresses the challenges of **processing diverse data types in resource-constrained environments**.
- The framework's adaptability, scalability, and real-time processing capabilities introduce new intelligent systems capable of operating **autonomously, adapting** to dynamic environments, and ultimately **enhancing human lives**.
- This research serves as a **foundation** for future innovations, inspiring further exploration and development in the rapidly evolving field of **AI and edge computing**.





## Journals

[J1] **D. Tsiktsiris**, A. Lalas, M. Dasygenis and K. Votis, “Multimodal Abnormal Event Detection in Public Transportation”, IEEE Access, 2024 **(Q1)**.

[J2] **D. Tsiktsiris**, A. Lalas, M. Dasygenis and K. Votis, “Enhancing the Safety of Autonomous Vehicles: Semi-Supervised Anomaly Detection with Overhead Fisheye Perspective”, IEEE Access, 2024 **(Q1)**.

[J3] **D. Tsiktsiris**, A. Lalas, M. Dasygenis and K. Votis, “Improving Passenger Detection with Overhead Fisheye Imaging”, IEEE Access, 2024 **(Q1)**.

[J4] T. Sanida, **D. Tsiktsiris**, A. Sideris, and M. Dasygenis. “A heterogeneous implementation for plant disease identification using deep learning”. In Multimedia Tools and Applications, vol. 81, p. 15041–15059, 2022 **(Q1)**.

[J5] T. Sanida, A. Sideris, **D. Tsiktsiris**, and M. Dasygenis. “Lightweight neural network for COVID-19 detection from chest X-ray images implemented on an embedded system”. In Technologies, vol. 10, p. 37, 2022 **(Q1)**.

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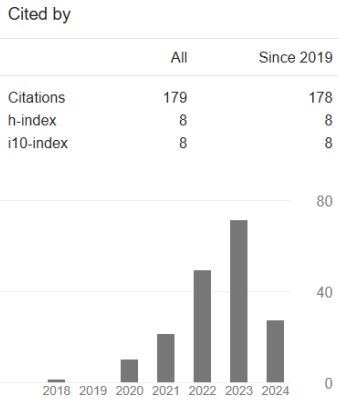
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**Thank You!  
Questions?**

